Computational Intelligence: Methods and Applications

Lecture 23
Logistic discrimination
and support vectors

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Logistic DA

Classification rule is therefore:

$$\Lambda = \frac{P(\omega_1 \mid \mathbf{X})}{P(\omega_2 \mid \mathbf{X})} > 1 \text{ Then Class } \omega_1 \text{ Else } \omega_2$$

or
$$\mathbf{W}^{\mathrm{T}}\mathbf{X} + W_0 > 0$$
 Then Class $\boldsymbol{\omega}_1$ Else $\boldsymbol{\omega}_2$

This time probabilities (observations) are non-linear functions of parameters W; usually iterative procedures based on maximization of likelihood of generation of the observed data are used, equivalent to:

$$L(\mathbf{W}, W_0) = \prod_{\mathbf{X} \in \omega_1} P(\omega_1 \mid \mathbf{X}) \prod_{\mathbf{X} \in \omega_2} P(\omega_2 \mid \mathbf{X})$$

Using logistic functions for $P(\omega|X)$ and calculating gradients in respect to W leads to a non-linear optimization problem.

This is implemented in WEKA/YALE, giving usually better results than LDA at some increase computational costs.

Logistic discrimination

Basic assumption of the logistic model: logarithm of the ratio of class distribution is a linear function:

$$\log \left(\frac{P(\mathbf{X} \mid \boldsymbol{\omega}_1)}{P(\mathbf{X} \mid \boldsymbol{\omega}_2)} \right) = \mathbf{W}^{\mathsf{T}} \mathbf{X} + W_0$$

This is exact when class distributions are normal (Gaussian) with equal covariance matrices, and for some discrete data distributions. Since these probabilities sum to 1, using the Bayesian formula $P(\omega|X) = P(X|\omega) P(\omega)/P(X)$, the model is equivalent to:

$$P(\boldsymbol{\omega}_{2} \mid \mathbf{X}) = \frac{1}{1 + \exp(\mathbf{W}^{\mathsf{T}} \mathbf{X} + W_{0}^{\mathsf{T}})}; \quad W_{0}^{\mathsf{T}} = W_{0} + \log \frac{P(\boldsymbol{\omega}_{1})}{P(\boldsymbol{\omega}_{2})}$$

$$P(\boldsymbol{\omega}_{1} \mid \mathbf{X}) = \frac{\exp(\mathbf{W}^{T}\mathbf{X} + W_{0}^{T})}{1 + \exp(\mathbf{W}^{T}\mathbf{X} + W_{0}^{T})} = 1 - P(\boldsymbol{\omega}_{2} \mid \mathbf{X})$$

WEKA Logistic voting

Similar results to LDA

Whole data:

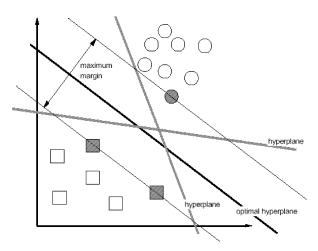
=== Confusion Matrix ===

a b <= classified as 260 7 | a = democrat 5 163 | b = republican

10xCV results

a b <= classified as 258 9 | a = democrat 9 159 | b = republican Decision trees give better results in this case, perhaps one hyperplane is not sufficient.

Maximization of margin 1



Among all discriminating hyperplanes there is one that is clearly better.

Maximization of margin 3

Maximize the distance $g_w(\mathbf{X})/||\mathbf{W}||$ between the plane \mathbf{W} and data samples, or maximize the value of discriminant $g_w(\mathbf{X})$ for $||\mathbf{W}||=1$ Find vectors $\mathbf{X}^{(i)}$ that are close to \mathbf{W} hyperplane in d dimensions:

$$\mathbf{X}^{(i)} = \arg\min_{\mathbf{X}} g_{\mathbf{W}}(\mathbf{X}) = \min_{\mathbf{X}} \left(\mathbf{W}^{\mathsf{T}} \mathbf{X} + W_{0}\right)$$

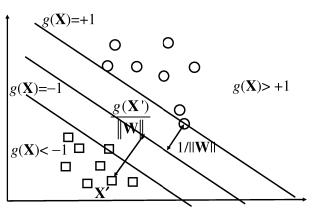
For these vectors find W giving maximum distance

$$\max_{\mathbf{W}} D(\mathbf{W}, \mathbf{X}^{(i)}) = \max_{\mathbf{W}} g_{\mathbf{W}}(\mathbf{X}^{(i)}) / ||\mathbf{W}||$$

Which vectors to choose as "support" for such calculation? Let the target values for classification be $Y(\omega_1)=+1$ and $Y(\omega_2)=-1$ and the margin b be the distance between W and these support vectors:

$$Y^{(i)} \frac{g_{\mathbf{W}}(\mathbf{X}^{(i)})}{\|\mathbf{W}\|} \ge b, \quad i = 1..n$$
 This should be true for all vectors, in a separable case.

Maximization of margin 2



 $g(\mathbf{X})=\mathbf{W}^{\mathrm{T}}\mathbf{X}+W_{0}$ is the discriminant function, $g(\mathbf{X})/||\mathbf{W}||$ is the distance. The best discriminating hyperplane should maximize the distance between the $g(\mathbf{X})=0$ plane and the data samples that are near to it.

Formulation of the problem

Setting $b||\mathbf{W}||=1$ (particular choice of b) separation conditions are:

$$Y^{(i)} g_{\mathbf{W}}(\mathbf{X}^{(i)}) \ge 1, \quad i = 1..n$$

These conditions define two canonical hyperplanes:

$$H_1: g_{\mathbf{W}}(\mathbf{X}) = \mathbf{W}^{\mathsf{T}} \mathbf{X} + W_0 = +1$$
 Distance of H_i from the H_0 separating $H_2: g_{\mathbf{W}}(\mathbf{X}) = \mathbf{W}^{\mathsf{T}} \mathbf{X} + W_0 = -1$ plane $g_{\mathbf{W}}(\mathbf{X}) = 0$ is $D(H_0, H_i) = 1/||\mathbf{W}||$

Largest margin is obtained from minimization of IIWII with $g_{\rm W}({\bf X})$, fulfilling the separation conditions.

This leads to a constrained minimization problem.

Minimize IIWII with constraints
$$Y^{(i)} g_{\mathbf{W}}(\mathbf{X}^{(i)}) \ge 1$$
, $i = 1..n$

Support vectors are vectors that are the closest to the separating hyperplane, most difficult to separate and most informative.

Scalar product form

In the d-dimensional space if n > d the weight vector may be expresses as the combination of:

$$\mathbf{W} = \sum_{i=1}^{n} \alpha_i \mathbf{X}^{(i)}$$

It should be enough to take only d independent training vectors, so most $\alpha = 0$. Therefore the discriminant function:

$$\begin{split} \boldsymbol{g}_{\mathbf{W}}\left(\mathbf{X}\right) &= \mathbf{W}^{\mathsf{T}} \mathbf{X} = \sum_{i} \alpha_{i} \mathbf{X}^{(i)\mathsf{T}} \cdot \mathbf{X} \\ \boldsymbol{g}_{\mathbf{W}}\left(\mathbf{X}^{(j)}\right) &= \mathbf{W}^{\mathsf{T}} \mathbf{X}^{(j)} = \sum_{i} \alpha_{i} \mathbf{X}^{(i)\mathsf{T}} \cdot \mathbf{X}^{(j)} \\ &= \sum_{i} \alpha_{i} K\left(\mathbf{X}^{(i)}, \mathbf{X}^{(j)}\right) = \sum_{i} \alpha_{i} K_{ij} \end{split}$$

The kernel matrix K_{ii} will play an important role soon ...

Scalar product discriminant

Differentiating in respect to W and W_0 gives:

$$\frac{\partial L(\mathbf{W}, \boldsymbol{\alpha})}{\partial W_0} = 0 \Rightarrow \sum_{i=1}^n \alpha_i Y^{(i)} = 0$$

$$\frac{\partial L(\mathbf{W}, \boldsymbol{\alpha})}{\partial \mathbf{W}} = 0 \Rightarrow \mathbf{W} = \sum_{i=1}^{n} \alpha_{i} Y^{(i)} \mathbf{X}^{(i)}$$

Interesting! W is now a linear combination of input vectors!

Makes sense, since a component W_Z of $W=W_Z+W_X$ that does not belong to the space spanned by $\mathbf{X}^{(i)}$ vectors has no influence on the discrimination process, because $\mathbf{W}_Z^T\mathbf{X}=0$.

Inserting **W** in the discriminant function:
$$g(\mathbf{X}) = \mathbf{W}^{\mathrm{T}} \cdot \mathbf{X} + W_0 = \sum_{i=1}^n \alpha_i Y^{(i)} \mathbf{X}^{(i)\mathrm{T}} \cdot \mathbf{X} + W_0$$

for support vector $Y^{(i)}g(\mathbf{X}^{(i)})=1$, so $W_0=Y^{(i)}-\mathbf{W}^{\mathrm{T}}\cdot\mathbf{X}^{(i)}$

Lagrange form and SV

Lagrange multiplier method is used to convert constraint minimization problems into a simpler optimization problem (here X includes $X_0=1$):

$$L(\mathbf{W}, \boldsymbol{\alpha}) = \frac{1}{2} \|\mathbf{W}\|^2 - \sum_{i=1}^{n} \alpha_i \left[Y^{(i)} g_{\mathbf{W}} \left(\mathbf{X}^{(i)} \right) - 1 \right], \, \alpha_i \ge 0, \quad i = 1..n$$

where α are Lagrangian multipliers - free positive parameters, and summation runs over the number of all training samples n.

Minimization of the Lagrangian function over W increases margin.

Suppose that $X^{(i)}$ is misclassification, then the second term $g(\mathbf{X}^{(i)})-1$ in the Lagrangian is negative, and large α_i will create a large contribution to $L(\mathbf{W}, \alpha)$; this will be decreased by changing W to remove the error. Therefore $||\mathbf{W}||$ should be minimized and α maximized, but only for vectors for which $g(\mathbf{X}^{(i)})-1=0$, called Support Vectors (SV).

This leads to the search for the saddle point, not minima; to simplify it W parameters are replaced by α .

Lagrangian in dual form

Substituting W into the Lagrangian leads to a maximization of a dual form (\mathbf{X} here may be d+1 dim or d-dim, it does not matter):

$$L(\boldsymbol{\alpha}) = \sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i=1}^{n} \alpha_i Y^{(i)} \sum_{i=1}^{n} \alpha_j Y^{(j)} \mathbf{X}^{(i)T} \cdot \mathbf{X}^{(j)}$$

$$\sum_{i=1}^{n} \alpha_{i} Y^{(i)} = 0; \quad \alpha_{i} \ge 0; \quad i = 1..n$$

In this form optimization criterion is expressed as inner products of support vectors, and is now **maximized** subject to constraints.

Initially number of parameters is equal to the number of patterns n, usually much bigger than dimensionality d, but the final number of non-zero α may be small.

This type of quadratic minimization problem has a unique solution!

Popular approach: SMO, Sequential Minimal Optimization algorithm for Quadratic Programming, fast and accurate.